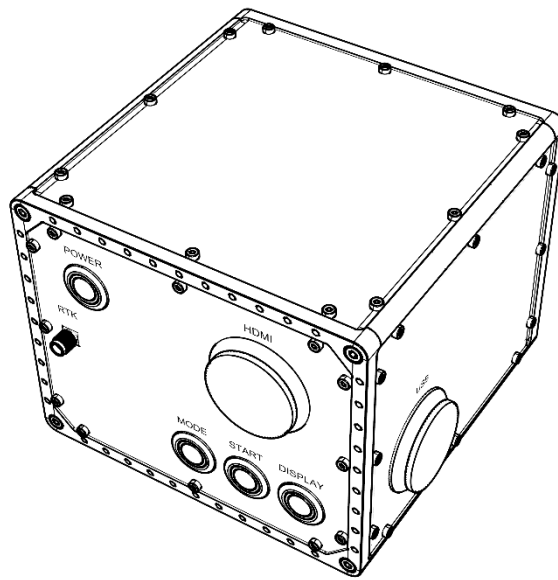


SPECIFICATION

Super Spectral Multisensor Drone Camera system



MSDC-2-4-SS
Version 01
April 20, 2024
Specifications subject to change

Table of Contents

| | |
|--------------------------------|----|
| Background information..... | 3 |
| Trademarks..... | 3 |
| Sales and Support..... | 3 |
| 1. Description | 4 |
| 2. Key Features | 5 |
| 3. Specifications | 6 |
| 4. Drawings..... | 7 |
| 5. Package Contents | 8 |
| 6. Software | 8 |
| Features..... | 9 |
| 7. Image Post-processing | 11 |

Background information

Trademarks

Spectral Devices Inc., MSDC, MSC2, MSDC-2-4, MSDC-2-4-SS

Sales and Support

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1. Description

The multisensor drone camera system (MSDC-2-4) is a turnkey multispectral imaging solution for easy integration with many drones enabling capture of geotagged aerial images for further analysis in data mapping software.

Each MSDC-2-4 (Fig.1a) includes up to 4 cameras with C-mount lenses optimized for customer specified field of view and ground resolution. All camera optical axis are aligned during the manufacturing process to ensure seamless image co-registration between cameras.

A built-in vision computer provides a high degree of control over the cameras, ensuring synchronized camera operation and image recording. System configuration is performed using simple text-based configuration files. Depending on the setup of the system, these settings can be modified by editing the files directly on a USB drive or an SD card before initiating the flight.

The MSDC-2-4 is equipped with a built-in GPS operating at 10 Hz and RTK base station enabling centimeter-level positional accuracy (Fig.1b). The system also incorporates a solar sensor (Fig.1b) with 19-channel spectrometer in UV-SWIR range, IMU providing 3-DOF sensor orientation and directional sensor for sun angle estimation.

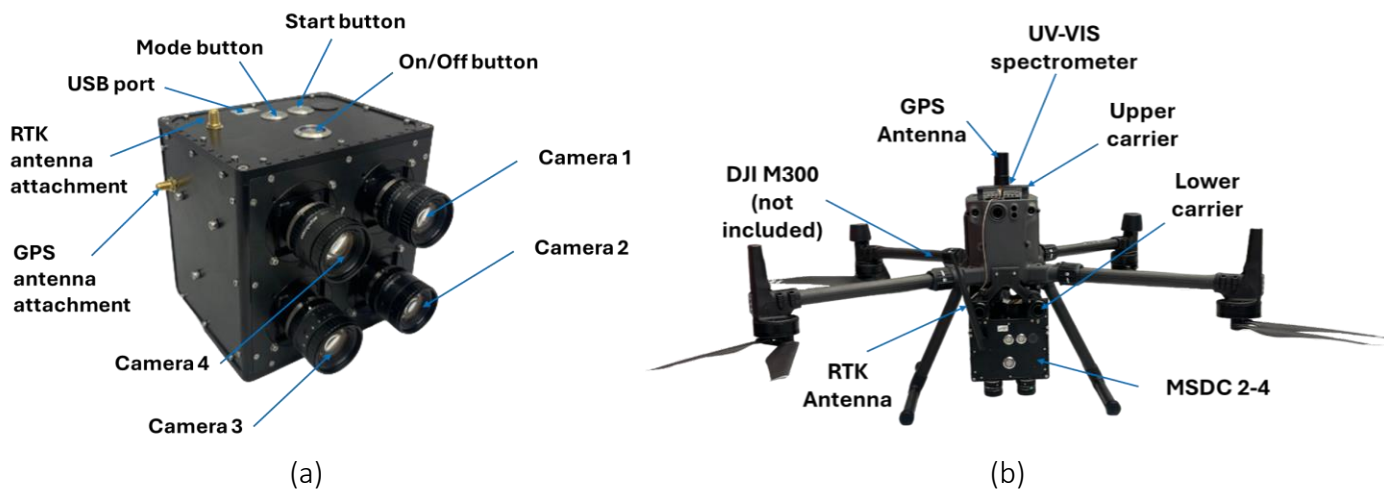


Figure 1. (a) MSDC 2-4 system. Note: position of switches and access ports is dependent on internal camera configuration. (b) MSDC-2-4 system mounted on a DJI M300 drone.

Operation of the system is simplified to only three pushbuttons – power, start, mode. The power button turns the system on or off. Start button starts and stops image acquisition and initiates computer shutdown. The Mode button cycles the system between image acquisition and computer shutdown mode.

Acquired images are saved on the USB drive or SD card (dependent on system configuration) and can be inspected using a PC and image post-processing software called msInspector. The software enables flight image and data (gps, solar) review and subsequent tagging with geo-location and radiometric correction data.

Although the system is designed to work with the DJI M300 RTK drone, integration on other drone models is possible if sufficient payload capacity (2 kg) and power (9-36V) is available.

The MSDC-2-4-SS-1-A drone camera system is designed for exploratory work requiring a large variety of wavelengths. Cameras has 3 visible wavelengths (445, 532, 645 nm), 8 near-infrared wavelengths (720, 760, 800, 840, 860, 900, 940, 980 nm), 16 shortwave infrared wavelengths (1125, 1160, 1195, 1230, 1265, 1300, 1335, 1370, 1405, 1440, 1475, 1505, 1540, 1575, 1605, 1640 nm) and thermal camera operation between 8-12 μm .

2. Key Features

- Diverse Camera Array
 - 8 - band NIR camera
 - Thermal camera
 - 16 - band SWIR camera
 - 5 MP narrow band Color camera
- Seamless Integration and User-Friendly Design
 - Compatible with a wide range of drones capable of carrying a payload of 1.7 kg and supplying 9 - 36V DC power
 - Designed with user-friendliness in mind, ensuring ease of use even for those new to drone technology
- Built-in Vision Computer
 - Real-time HDMI output of multispectral images
 - Sustained frame rates of up to 1 FPS with simultaneous recording to USB drive or SD card
 - Over 4 h of sustained frame recording at 1 FPS with a 512 GB USB drive (12-bit mode)
- Built-in GPS
 - High performance GPS with 10 Hz update rate
 - Includes RTK base station for centimeter-level accuracy and 20 km range
- Solar sensor
 - 19 channel spectrometer
 - Built-in IMU for orientation
 - Built-in directional sensor
- Enables comprehensive analysis of multispectral data
 - Agricultural and environmental monitoring: NDVI, GNDVI, EVI, MSAVI, NDWI, MSI, NDMI, NBI
 - Thermal monitoring
 - Structural and infrastructure inspections
 - Archeological exploration
- Advanced Post-Processing Software
 - The system comes equipped with sophisticated image post-processing software
 - Provides the radiometric correction data and adds it to the image metadata
 - Geotagging for precise location mapping
 - Support provided for orthomosaic map generation

3. Specifications

Table 1. List of cameras in the MSDC-2-4-SS system

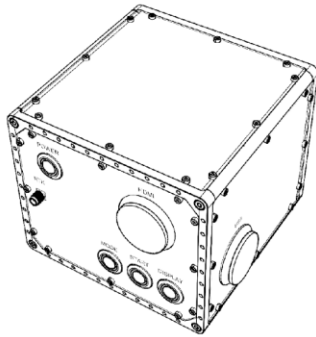
| CAMERA | TYPE | #BANDS | RESOLUTION/BAND | BANDS | BANDWIDTH (FWHM) |
|---------|-----------|--------|-----------------|---|---------------------|
| NIR | Area scan | 8 | 256 x 256 | 720, 760, 800, 840, 860, 900, 940, 980 nm | 20 nm |
| SWIR | Area scan | 16 | 135 x 105 | 1125, 1160, 1195, 1230, 1265, 1300, 1335, 1370, 1405, 1440, 1475, 1505, 1540, 1575, 1605, 1640 nm | 5-45 nm |
| Thermal | Area scan | 1 | 1280 x 1024 | Thermal | 8-12 μ m |
| COLOR | Area scan | 3 | 2448 x 2048 | 445 nm, 532 nm, 645 nm | 35 nm, 25 nm, 60 nm |

Table 2. Specifications of the MSDC-2-4-SS system

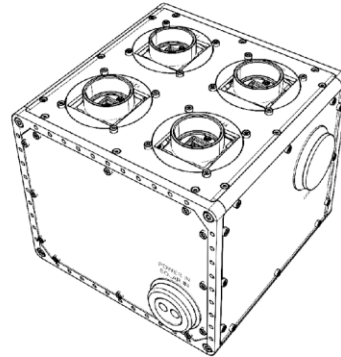
| | |
|-----------------------|--|
| Lens compatibility | All Spectral Devices C-mount lenses |
| Thermal control | Passive conduction of camera heat to enclosure |
| Water-resistant | Yes (IP54) |
| Dust-resistant | Yes (IP54) |
| Connector access | USB, SD card, HDMI, power cable, two SMA connectors for GPS antenna and RTK antennas |
| External construction | Aluminum with Stainless-steel hardware |
| Surface finish | Black anodization with laser etching |
| Dimensions | 136 mm x 136 mm x 110 mm (150 mm with lenses) |
| Weight | 1.70 kg with lenses. 1.38 kg without lenses |
| Power input | 9 - 36 V DC directly from the drone |
| Image Geolocation | GPS/GNSS @ 10Hz |
| Frame rate | up to 1 FPS with simultaneous recording to USB drive or SD card |

4. Drawings

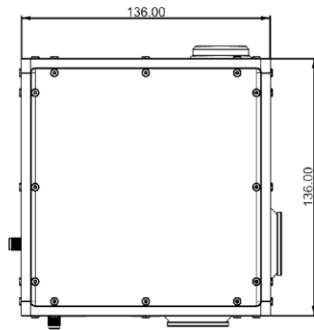
RENDERED TOP VIEW



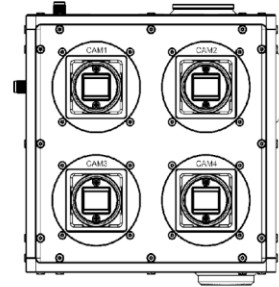
RENDERED BOTTOM VIEW



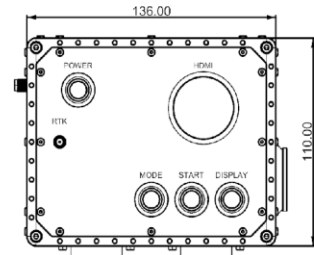
TOP VIEW



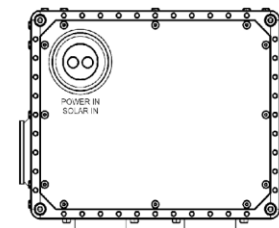
BOTTOM VIEW



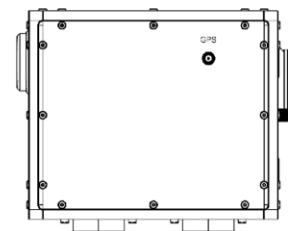
FRONT VIEW



BACK VIEW



LEFT VIEW



RIGHT VIEW

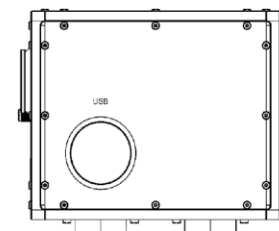


Figure 2. MSDC-2-4 system drawings.

5. Package Contents

Package contents are listed in Table 3 and shown in Fig.3a. All items are supplied in a waterproof equipment case (Fig.3b).

Table 3. MSDC-2-4-SS package contents

| | |
|------------------------|---|
| MSDC-2-4-SS | As shown in Fig.1a. |
| Lower carrier | Attachment for MSDC-2-4 to the drone |
| Upper carrier | Attachment for the solar sensor, GPS antenna to the drone and accommodates power regulator board for power connection between the payload and the drone |
| Two GPS Antennas | Attaches to MSDC-2-4 and RTK base station |
| RTK antenna | Attaches to RTK base station |
| RTK base station | Improves GPS accuracy |
| Two 256 GB SD cards | Used for image saving during flights |
| SD card adapter | For connection to most PC SD card slots |
| Solar sensor | Attaches to the upper carrier and connects to the MSDC-2-4 via USB3.0 |
| Power cable | Connects MSDC-2-4 to the power regulator board in the upper carrier |
| Hex keys | Necessary keys for MSDC-2-4 attachment to the drone |
| Protective lens covers | Protects lenses when not in use |

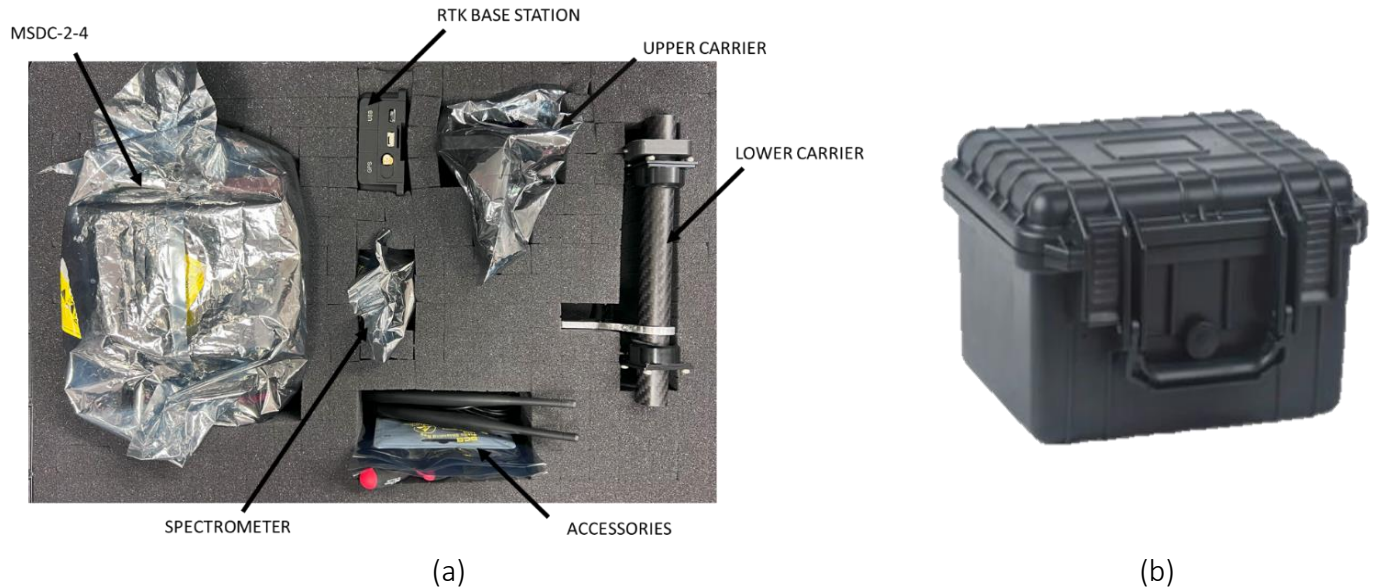


Figure 3. (a) MSDC-2-4 system package and its contents, (b) waterproof equipment case.

6. Software

With every MSDC-2-4, Spectral Devices provides mslInspector, a Windows-based application featuring a graphical user interface (GUI). The software makes inspection and geotagging of images collected with the MSDC series multispectral drone cameras from Spectral Devices Inc quick and easy.

The software onboard the MSDC-2-4 performs real-time preprocessing of images from each camera. For example, multispectral images are demosaiced and saved in TIFF format onto the removable USB drive or SD

card. While single band cameras, such as the SWIR and Red Edge are saved directly to the drive. Images are saved into a hierarchical folder system ensuring no data is overwritten between flights.

msInspector uses configuration, calibration, and correction files specific to each MSDC-2-4 camera. The calibration and correction files are supplied by Spectral Devices. msInspector provides a series of batch operations allowing the user to load images, solar sensor data, and GPS data. At each step, data can be visualized. Lastly, the GPS and solar data can be written into the image metadata.

Features

1. Simple, easy to use tabbed GUI.
2. Data visualization (images, GPS and solar sensor data)
3. Geotags large numbers of images in a single operation.
4. Tags solar sensor data to the images for radiometric calibration.
5. Exports geotagged images in multiple formats to the desired folder.
6. Provides tags required by 3rd party mapping software.

In the msInspector Camera tab the user can review all the collected images and apply non-uniformity corrections to the images (Fig.4).

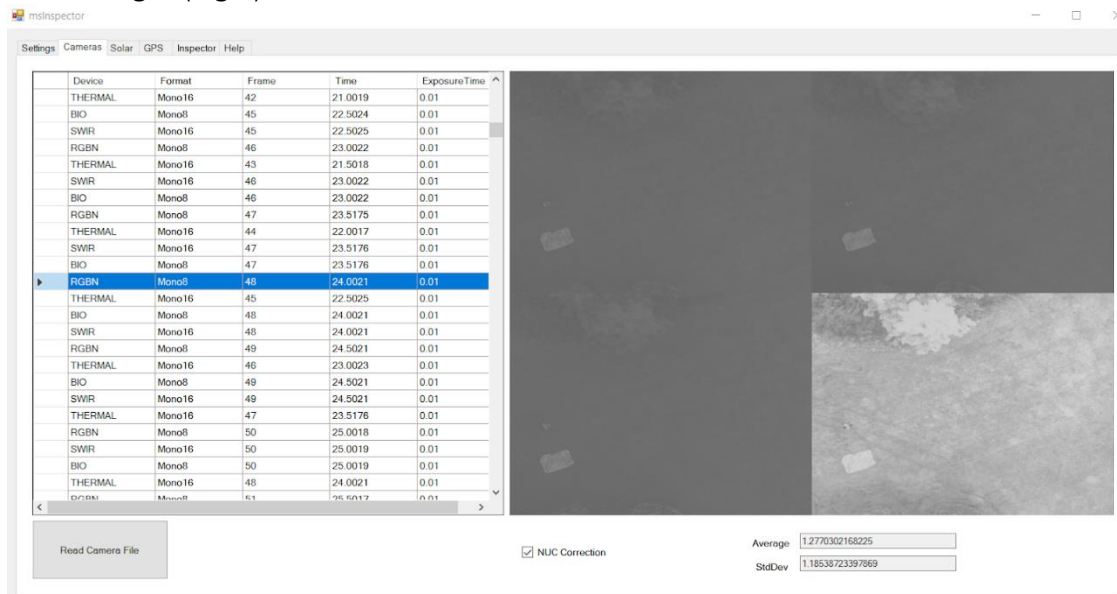


Figure 4. Camera tab in the msInspector.

Solar tab (Fig.5) in the msInspector allows user to review data collected by the solar sensor during the flight. Data includes the spectrometer reading across the VIS-NIR spectrum, sensor orientation (yaw, pitch, roll), and solar direction relative to the sensor.

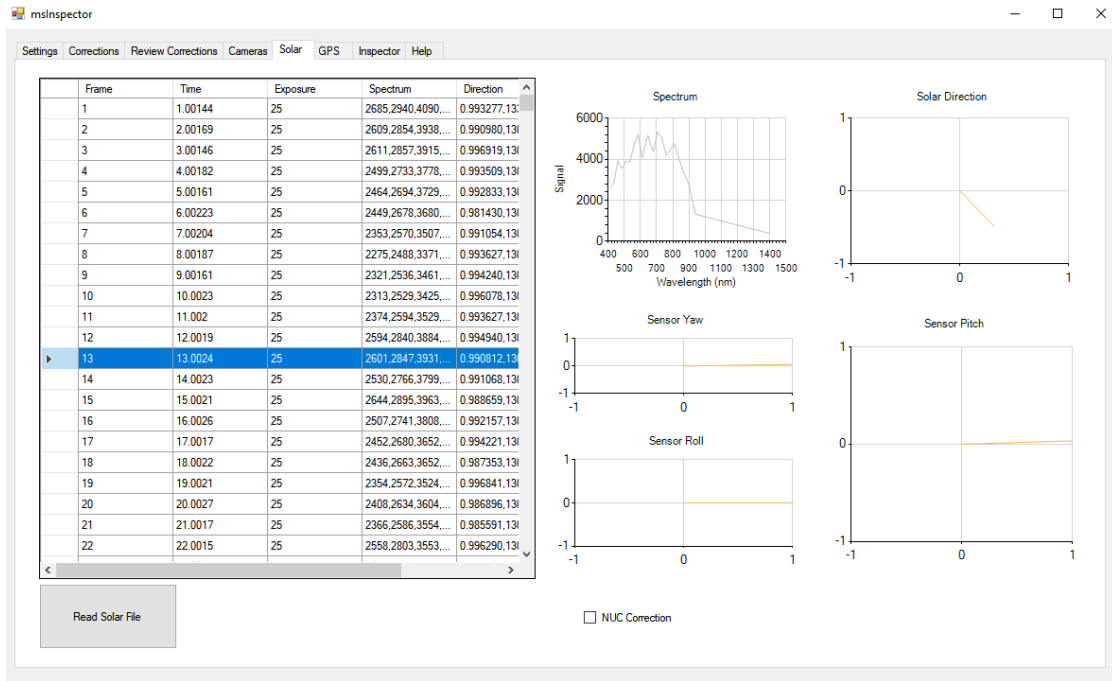


Figure 5. Solar tab in the msInspector.

GPS tab (Fig.6) in the msInspector allows the user to review GPS data collected by the GPS sensor (longitude, latitude, and altitude) during the flight. A map is displayed showing the location of the flight along with the flight path.

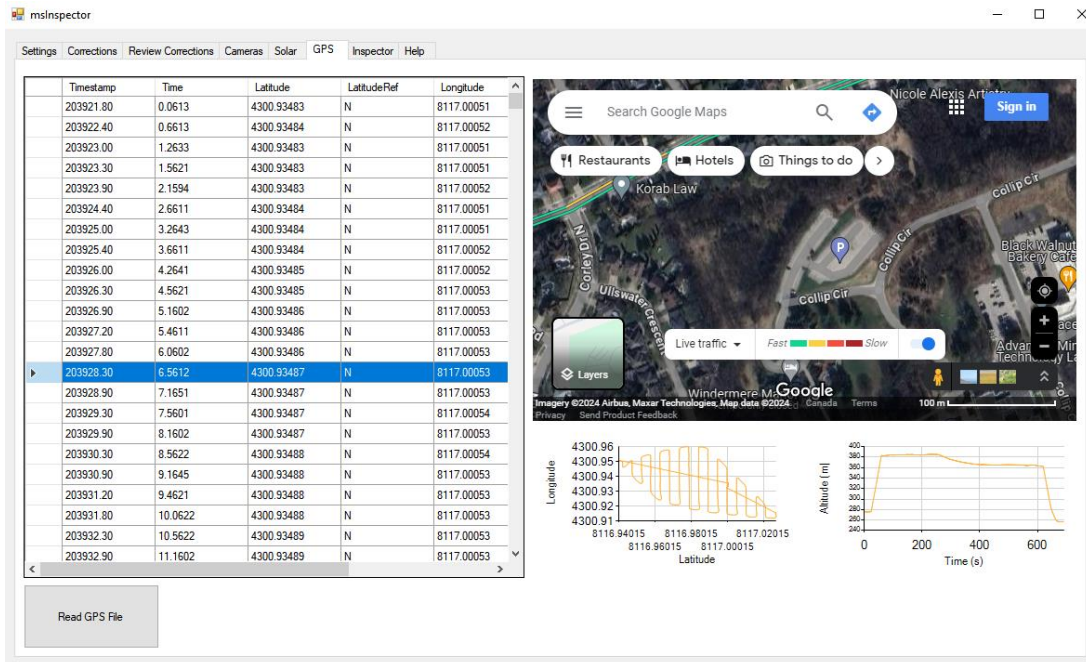


Figure 6. GPS tab in the msInspector.

The Inspector tab (Fig.7) in the msInspector allows the user to review all the data together. This data is used for image metadata generation. From this tab, geotagged images are exported with all the necessary metadata for image post-processing using software such as WebODM or Pix4DFields.

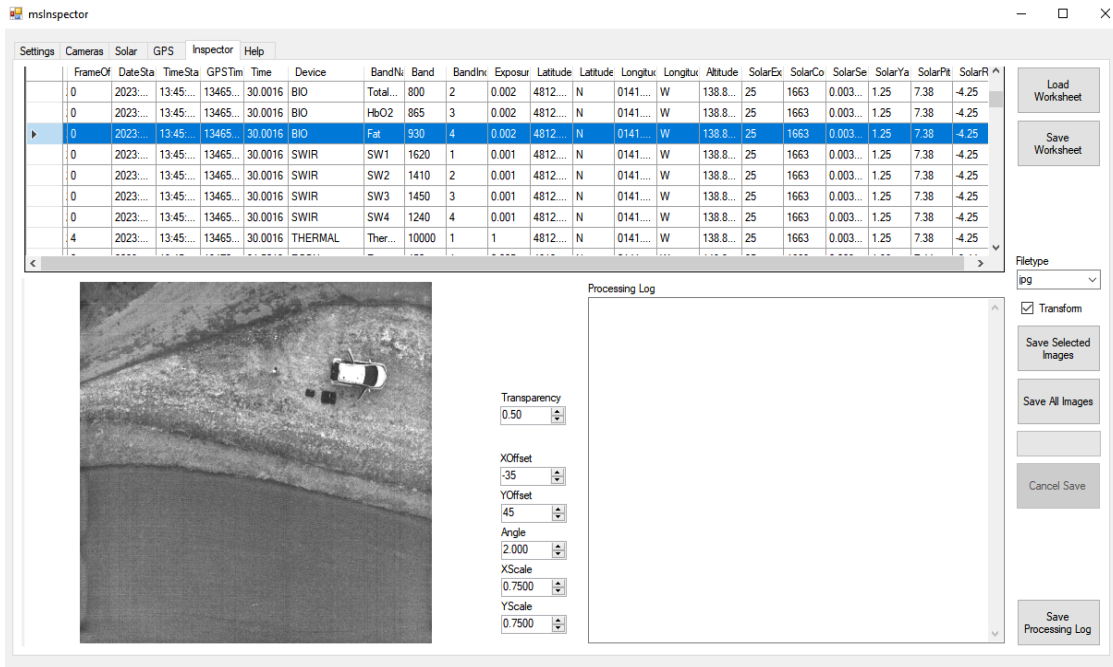


Figure 7. GPS tab in the mslInspector.

7. Image Post-processing

Images exported from the mslInspector are ready for 3D model reconstruction and orthomosaic map generation using open-source software WebODM by Open Drone Maps or subscription software Pix4D.

Spectral Devices Inc. provides tutorials and guides for image post-processing.